

MOTOMAN YRC1000

Industrial Robot Controller



High Performance Controller YRC1000 for MOTOMAN Robots

The MOTOMAN YRC1000 is a compact, fast and flexible controller for MOTOMAN robots that combines high performance robot control in a small footprint cabinet with volume of 125 litres and a maximum weight of 70 kg.

Besides the typical YASKAWA controller functionality, the YRC1000 includes additional functional improvements. Speed of the controller has been increased by lowering a ladder scanning time.

Path accuracy improvement assures increased precision in trajectory performance independently on the motion speed.

User interface supports smartphone like touch operations and allows the user to 3D simulate robots motion on PP screen before and during execution of the real robot arm. Service staff can directly connect to the PP user interface for remote service purposes. Total programming pendant's weight was reduced to 730 grams which offers more convenient use by the operator. The new controller simplifies maintenance by offering preventive maintenance information and powerful software tools for analysis and notification.

Key benefits

- · Compact, fast and flexible
- Global standardization (no transformer required)
- · High path accuracy
- High efficiency

Optimal Industrial Design

· Volume: 125 liters



Programming Pendant (PHG) – ergonomical, light and easy





specifications controller yRC1000

Specifications controlle	, jito tooo
Dimensions	598 (W) x 490 (H) x 427 (D) mm (125 l without protrusion parts)
Weight	70 kg max. (possible to control three external axes)
Protection class	IP54
Cooling system	Indirect cooling
Ambient temperature	During operation: 0°C to +45°C / During storage: -10°C to +60°C
Relative humidity	90 % max. (non-condensing)
Power supply	Three-phase 380-440 VAC (+10 %, -15 %), 50/60 Hz (±2 %)
Digital i/Os	Specialized signals: 19 inputs and 6 outputs / General signals: 40 inputs and 40 outputs
Programming capacity	JOB: 200,000 steps, 10,000 instructions / CIO ladder: 20,000 steps
expansion slots	2 x PCle or 2 x PCl or 1 x PCl/1 x PCle
LAn	
(Connection to host)	2 (10BASE-T/100BASE-TX)
interface	RS-232C/RS422: 1ch (used by switching)

Common Size for use in Japan, Asia, Europe, and the U.S.



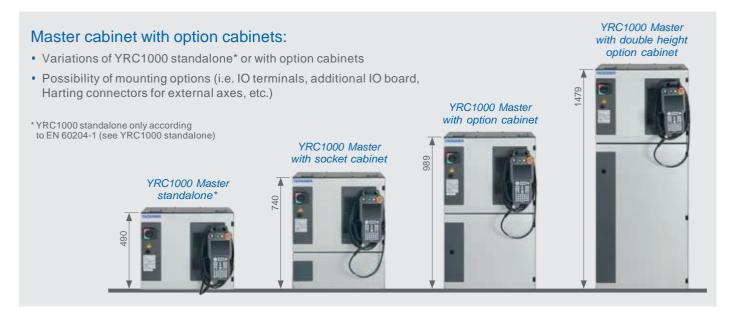
Improved Programming Pendant



specifications programming pendant		
Dimensions	152 (W) x 299 (H) x 53 (D) mm	
Weight	0.730 kg	
Material	Reinforced plastics	
Operation device	Select keys, axis keys, numerical/application keys, mode selector switch with keys (mode: teach, play, and remote), emergency stop button, enable switch, SD card interface device, USB port (1 port)	
Display	5.7-inch color LCD, touch panel 640 x 480 pixels	
ieC protection class	IP54	

MOTOMANYRC1000-Options

YRC1000 Design Concept



YRC1000 Standalone

Master cabinet standalone:

- In case that YRC1000 is a main cabinet in the system (i.e. Main switch of the cabinet is also main switch of the whole system), YRC1000 cannot stand on the servicing level directly
- EN 60204-1 states minimum position of the system's main switch with respect to the servicing level, as well as minimum height of cables connected to the cabinet above the servicing level



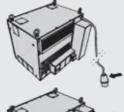
Dimensions in mm

YRC1000 Power Supply Variants



1. Direct connection (option):

- Connection is made directly to the main switch, the cable goes through an opening at the back side of the YRC1000 cabinet at the upper right corner
- Connection inside the controller can be made by electrician only



2. CEE connector with a cable (option):

- YASKAWA can deliver YRC1000 cabinet with CEE socket, plug and cable (L = 5 m)
- · No additional wiring in the controller is needed

3. CEE connector at the cabinet (standard):

- CEE socket is mounted at the CEE hood at the back side of the YRC1000 cabinet
- · No additional wiring in the controller is needed

YRC1000 Robot Cable Variants



1. Straight cable at controller side/straight cable at robot side:

- Robot cable connector is straight on controller side
- Robot cable connector is straight on robot side
- This configuration does allow any space under the cable and cable connector
- This configuration may restrain area behind the controller due to the robot cable bending ratio (R = 270 mm)



2. Angled cable at controller side/straight cable at robot side:

- · Robot cable connector is angled on controller side
- Robot cable connector is straight on robot side
- This configuration requires free space under the cable and cable connector
- Can be used in case that YRC1000 controller is elevated by means of socket cabinet or other stand
- This configuration does not require additional space behind the controller other than free space required by mounting instructions (cooling of the cabinet)

YRC1000 Controller Module Options

Visual	name	Dimension	Artno. 1	Artno. 2
	Socket cabinet with angled connector plate	H = 250 mm	191963	143815100
	Cabinet with angled connector plate	H = 499 mm	191965	143816100
	Cabinet without angled connector plate		191966	143817100
	Cabinet with angled connector plate, double height	H = 989 mm	191967	143816110

MOTOMANYRC1000-Options

YRC1000 Socket Cabinet Options

Visual	name	Description	Artno. 1	Artno. 2
	Drawer for socket cabinet	Backside of the cabinet, drawer used for easy access into the socket (mounting of IO terminals)	187154	143818100
	Mounting plate in socket cabinet, C-rail and other components	Fixing element in the dawer	187155	143889100
YASKAWA		wer ck side ne cabinet)	Mounting plate for the drawer	IO terminals (with and without relay)

YRC1000 H = 499 mm and H = 989 mm Cabinet Options

Visual	name	Description	Artno. 1	Artno. 2
	Swingframe for standard cabinet, H = 499 mm	Inside the cabinet for easy access, plate for IO terminals mounting	187156	144270100
	Swing frame (high) for double height cabinet, H = 989 mm		187157	144270110

YRC1000 Option Cabinet – available Equipment

Master cabinet with socket cabinet:

socket cabinet with height of 250 mm

- 4 x IO transfer element (with and without relay)
- Full version of Cable Set A incl. FSU signals
- · Full version of Cable Set B
- · FSU transfer element
- · Conveyor cabling
- · Connectors for external axes (max. 3)



Master cabinet with option cabinet H = 499 mm with or without angled connector plate:

Option cabinet with height of 499 mm

- 4 x IO transfer element (with and without relay) on a swing frame
- · Full version of cable set A incl. FSU
- Full version of cable set B
- FSU transfer element
- · Conveyor cabling
- Connectors for external axes (max. 3)
- · Additional IO board
- Mounting plate for additional equipment
- Mounting plate as a swing frame for additional equipment (option)



Master cabinet with option cabinet H = 989 mm:

Option cabinet with height of 989 mm

- 4 x IO transfer element (with and without relay) on a swing frame
- · Full version of cable set A incl. FSU
- · Full version of cable set B
- · FSU transfer element
- Conveyor cabling
- · Connectors for external axes (max. 3)
- Additional IO board
- Mounting plate for additional equipment
- Mounting plate as a swing frame for additional equipment (option)



YASKAWA GROUP

- AT YASKAWA Austria Schwechat/Wien +43(0)1-707-9324-15
- CZ YASKAWA Czech s.r.o. Rudná u Prahy +420-257-941-718
- ES YASKAWA Ibérica, S.L. Gavà/Barcelona+34-93-6303478
- FR YASKAWA France SARL Le Bignon +33-2-40131919
- FI YASKAWA Finland Oy Turku +358-(0)-403000600
- GB YASKAWA UK Ltd. Banbury +44-1295-272755
- IT YASKAWA Italia s.r.l. Torino +39-011-9005833
- IL YASKAWA Europe Technology Ltd. Rosh Ha'ayin +972-3-9004114
- NL YASKAWA Benelux B.V. Eindhoven +31-40-2895500
- PL YASKAWA Polska Sp. z o.o. Wrocław +48-71-7928670
- RU YASKAWA Europe Holding AB Moskva +46-480-417-800
- SE YASKAWA Nordic AB Torsås +46-480-417-800
- SI YASKAWA Slovenia Ribnica +386-1-8372-410
- TR YASKAWA Turkey Elektrik Ticaret Ltd. Sti. İstanbul +90-216-5273450
- ZA YASKAWA Southern Africa (PTY) Ltd Johannesburg +27-11-6083182

DISTRIBUTORS

- BG ARAMET ROBOTICS Ltd. Yambol +359-885 317 294
 - Kammarton Bulgaria Ltd. Sofia +359-02-926-6060
- DK Robotcenter Danmark Løsning +45 7022 2477
- EE RKR Seadmed OÜ
 Tallinn/Estonia+372-68-35-235
- GR Gizelis Robotics Schimatari Viotias +30-2262057199
- HU Flexman Robotics Kft Budapest +36 1 259 0981
- LT Profibus UAB
 Panevezys +370-45-518575
- NO Skala Robotech AS Lierstranda +47-32240600
- PT ROBOPLAN Lda Aveiro +351-234 943 900
- RO Sam Robotics srl Timisoara +40-720-279-866

MPL Automation S.R.L. Satu Mare +40 (0) 261 750 741





YASKAWA Headquarters

YASKAWA Europe GmbH Robotics Division Yaskawastraße 1 85391 Allershausen, Germany Tel. +49 (0) 8166/90-0 Fax +49 (0) 8166/90-103

YASKAWA ACADEMY and sales office Frankfurt

YASKAWA Europe GmbH Robotics Division Hauptstraße 185 65760 Eschborn, Germany Tel. +49 (0) 6196/77725-0 Fax +49 (0) 6196/77725-39 All drawing dimensions in mm.
Technical data may be subject to change without previous notice.
Please request detailed drawings at robotics @ yaskawa.eu.com.

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